

Finalist of Best Paper award for ICARCV 2010

- Paper ID: P0210
Authors: Zhiyong Chen, Hai-Tao Zhang, Chao Zhai
Paper Title: Asymptotic Synchronization and Collision Avoidance for Multi-agent Flocking
- Paper ID: P0281
Authors: Dawei Li, Lihong Xu and Erik Goodman
Paper Title: Online Background Learning for Illumination-robust Foreground Detection
- Paper ID: P1114 (winner)
Authors: Zhuo YANG and Sei-ichiro KAMATA
Paper Title: Fast Polar Harmonic Transforms
- Paper ID: P0356
Authors: Matthias Ruther, Martin Lenz and Horst Bischof
Paper Title: The Narcissistic Robot: Robot Calibration Using a Mirror
- Paper ID: P0267
Authors: Pal Liljeback, Kristin Y. Pettersen, Øyvind Stavdahl, Jan Tommy Gravdahl
Paper Title: Experimental Investigation of Fundamental Properties of Snake Robot Locomotion
- Paper ID: P0381
Authors: Tri Tran, Hung T. Nguyen, and Q.P. Ha
Paper Title: Stability of Complex Systems with Mixed Connection Configurations under Shared Control