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Miroslav Krstic is the Daniel L. Alspach Professor at UC San Diego and the founding director of the Cymer Center for Control Systems and Dynamics. He is a co-author of *Nonlinear and Adaptive Control Design* (1995), one of the two most cited research monographs in the history of control engineering, the new single-authored *Delay Compensation for Nonlinear, Adaptive, and PDE Systems* (2009), and six other books on control of turbulent fluid flows, stochastic nonlinear systems, and extremum seeking. Krstic has held the Springer Distinguished Visiting Professorship at UC Berkeley and the Sorenson Distinguished Professorship at UCSD. He is a Fellow of IEEE and IFAC, a recipient of the PECASE, NSF Career, ONR Young Investigator, Axelby, and Schuck awards, and the first engineering recipient of the UCSD Research Award. Krstic serves as Senior Editor of *IEEE Trans. Automatic Control* and *Automatica* and as Editor of the Springer-Verlag book series *Communications and Control Engineering*.

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